Cartan-Karlhede algorithm and Cartan invariants for spacetimes III

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Outline

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- Spinor transformations
- Covariant derivatives and curvature spinors
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An example in 4D

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- First and second order
- Higher orders



The alignment classification

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From spinors to NP tetrads

For an arbitrary spin basis, (o, ι) , such that $[o, \iota] = 1$ then we can consider Sp(1) transformations to construct a new spin basis

In particular, using the Petrov classification for Weyl spinors, we can use these transformations to align the spin frame with the Weyl spinor.

Using the Infeld-van der Waerden symbols we can relate this to a NP frame $\{\ell, n, m, \bar{m}\}$:

$$\ell^{a} = o^{A}\bar{o}^{A'}, \ n^{a} = \iota_{A}\bar{\iota}^{A'}, \ m^{a} = o^{A}\bar{\iota}^{A'}, \ \bar{m}^{a} = \iota^{A}\bar{o}^{A'},$$

$$\ell_{a} = o_{A}\bar{o}_{A'}, \ n_{a} = \iota_{A}\bar{\iota}_{A'}, \ m_{a} = o_{A}\bar{\iota}_{A'}, \ \bar{m}_{a} = \iota_{A}\bar{o}_{A'},$$

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Lorentz frame transformations

For the NP basis $\{\ell, n, m, \overline{m}\}$ where

$$g_{ab} = 2\ell_{(a}n_{b)} - m_{(a}\bar{m}_{b)}, \tag{2}$$

the Lorentz frame transformation group is then:

Boosts and Spins:

$$\ell' = a^2 \ell, \ n' = a^{-2} n, m' = e^{2i\theta} m.$$
 (3)

• Null rotations about *l*:

$$\ell' = \ell, \ n' = n + bm + \bar{b}\bar{m} + |b|^2\ell, m' = m + \bar{b}\ell.$$
 (4)

• Null rotations about n:

$$n' = n, \ \ell' = \ell + cm + \bar{c}\bar{m} + |c|^2 n, m' = m + \bar{c}n.$$
 (5)

These are the corresponding transformations we would use to build a frame adapted to the Petrov classification of the Weyl tensor.

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How to differentiate a spinor

If θ , ϕ and ψ are spinor fields defined on M, where θ and ϕ have the same valence. The spinor covariant derivative is defined as a map $\nabla_x = \nabla_{XX'} : \theta_{\dots} \to \theta_{\dots;XX'}$ such that

- $\nabla_x(\theta + \phi) = \nabla_x \theta + \nabla_x \phi$
- $\nabla_{\mathbf{X}}(\theta\psi) = (\nabla_{\mathbf{X}}\theta)\psi + \theta\nabla_{\mathbf{X}}\psi.$
- $\psi = \nabla_{\mathbf{X}} \theta$ implies $\overline{\psi} = \nabla_{\mathbf{X}} \overline{\theta}$
- $\nabla_x \epsilon^{AB} = \nabla_x \epsilon_{AB} = 0$
- ∇_X commutes with any index substitution not involving X or X'
- $\nabla_x \nabla_y f = \nabla_y \nabla_x f$ for *f* a scalar (torsion-free)
- For any derivation *D* acting on spinor fields, there is a spinor $\zeta^{XX'}$ such that $D\psi = \zeta^{XX'} \nabla_{XX'} \psi$ for all ψ .

This identifies the 4D vector space of Hermitian spinors $\tau^{AA'}$ with $T_{\rho}(M)$ and the dual vector space with $T^*_{\rho}(M)$

Good news: ∇_x exists and is unique [Penrose and Rindler 1984, section 4.4].

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Detour into frame fields

The tetrad formalism is one way to compute the curvature tensor.

Suppose that e^{i}_{a} is a tetrad of vectors, with corresponding dual e^{a}_{i} , so that

$$e_i^a e_b^i = \delta_a^b.$$

i, *j*, *k*, *l* label the (co)vectors.

a, b, c, d label the components with respect to some arbitrary chosen basis.

The Ricci rotation coefficients are then

$$\Gamma_{ijk} = e_i^{\ a} e_k^{\ b} \nabla_b e_j^{\ a} = -e_j^{\ a} e_k^{\ b} \nabla_b e_i^{\ a}. \tag{6}$$

where $\boldsymbol{\nabla}$ is the Levi-Civita connection for tensors.

From the Ricci identity we have

$$R_{abcd} = 2e_{ia} \nabla_{[c} \nabla_{d]} e^{i}{}_{b}.$$
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Spinor dyads

Introduce the spinor dyad ϵ_l^A and its symplectic dual ϵ_A^l so that

$$\epsilon_0^A = o^A, \ \epsilon_1^A = \iota^A, \ \epsilon_I^A \epsilon_B^I = \epsilon_B^A.$$

Then the spinor Ricci rotation coefficients are

$$\Gamma_{IJKK'} = \epsilon_{IA} \epsilon_K^{\ C} \epsilon_{K'}^{\ C'} \nabla_{CC'} \epsilon_J^{\ A} \tag{8}$$

The spinor equivalent of the curvature tensor is then

$$\begin{aligned} R_{ABCDA'B'C'D'} &= 2\epsilon_{IA}\epsilon_{I'A'} \nabla_{[c} \nabla_{d]} (\epsilon_{B}^{I} \epsilon_{B'}^{I'}) \\ &= 2\epsilon_{IA}\epsilon_{I'A'} \epsilon_{B'}^{I'} \nabla_{[c} \nabla_{d]} \epsilon_{B}^{I} + \text{c.c.} \end{aligned}$$
(9)
$$&= 2\epsilon_{IA}\epsilon_{A'B'} \nabla_{[c} \nabla_{d]} \epsilon_{B}^{I} + \text{c.c.} \end{aligned}$$

Here, $\nabla_{\textit{c}} = \nabla_{\textit{CC}'}$ and $\nabla_{\textit{d}} = \nabla_{\textit{DD}'}$ and this can be rewritten as

$$R_{ABCDA'B'C'D'} = \epsilon_{IA}\epsilon_{A'B'}(\epsilon_{C'D'}\Box_{CD}\epsilon'_B + \epsilon_{CD}\Box_{C'D'}\epsilon'_B) + \text{c.c.}$$

where $\Box_{CD} = \nabla_{C'(C} \nabla_{D)}^{C'}$ and $\Box_{C'D'} = \nabla_{C(C'} \nabla_{D'}^{C})$.

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Curvature spinor

The first term $\epsilon_{IA} \Box_{CD} \epsilon^{I}{}_{B}$ is symmetric in *CD* and *AB*.

This tensor can be decomposed as

$$\epsilon_{IA} \Box_{CD} \epsilon_{B}^{I} = \Psi_{ABCD} - 2\Lambda \epsilon_{(A(C} \epsilon_{D)B)}.$$
(10)

where

$$\Psi_{ABCD} = \epsilon_{IA} \Box_{(CD} \epsilon^{I}{}_{B)}, \quad \Lambda = \frac{1}{6} \epsilon_{IA} \Box^{AB} \epsilon^{I}{}_{B}. \tag{11}$$

Similarly, the second term can be written as

$$\epsilon_{IA} \Box_{C'D'} \epsilon^{I}{}_{B} = \Phi_{ABC'D'} \tag{12}$$

which is symmetric in AB and C'D'.

Thus the curvature spinor can be written as

$$R_{ABCDA'B'C'D'} = \epsilon_{A'B'}\epsilon_{C'D'} [\Psi_{ABC} - 2\Lambda\epsilon_{(A(C)}\epsilon_{D)B}] + \epsilon_{A'B'}\epsilon_{CD}\Phi_{ABC'D'} + \text{c.c.}$$
(13)

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Components of the curvature spinor

$$R_{ABCDA'B'C'D'} = \epsilon_{A'B'}\epsilon_{C'D'} [\Psi_{ABC} - 2\Lambda\epsilon_{(A(C)}\epsilon_{D)B)}] + \epsilon_{A'B'}\epsilon_{CD}\Phi_{ABC'D'} + \text{c.c.}$$
(14)

From $R_{a[bcd]} = 0$, it follows that $\Lambda \in \mathbb{R}$ and $\Phi_{ABA'B'}$ is Hermitian.

Contracting two indices, we have

$$R_{ABA'B'} = -2\Phi_{ABA'B'} + 6\Lambda\epsilon_{AB}\epsilon_{A'B'} \leftrightarrow R_{ab} = -2\Phi_{ab} + 6\Lambda g_{ab}$$
(15)

and so we recover the Ricci scalar and the trace-free Ricci tensor:

$$\Lambda = \frac{R}{24}, \ \Phi_{ab} = -\frac{1}{2} \left(R_{ab} - \frac{1}{4} R g_{ab} \right).$$
 (16)

The remaining term is a Hermitian spinor which gives the Weyl tensor

$$\Psi_{ABC}\epsilon_{A'B'}\epsilon_{C'D'} + \text{c.c.}$$
(17)

The differential Bianchi identities, $R_{ab[cd;e]} = 0$ give

$$\nabla^{D}_{C'}\Psi_{ABCD} = \nabla^{D'}_{(C}\Phi_{AB)C'D'}, \quad \nabla^{BB'}\Phi_{ABA'B'} = -3\nabla_{AA'}\Lambda.$$
(18)

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Spin coefficients

Rewrite quantities explicitly using a particular NP frame and associated derivatives:

$$D = \ell^a \nabla_a, \ \Delta = n^a \nabla_a, \delta = m^a \nabla_a, \ \bar{\delta} \nabla_a \tag{19}$$

Then the (spinor) Ricci rotation coefficients can be written down as 12 complex-valued scalars:

$\nabla_{BB'}$	0 ^A ∇ _{BB'} 0 _A	$o^A \nabla_{BB'} \iota_A = \iota^A \nabla_{BB'} o_A$	$\iota^A \nabla_{BB'} \iota_A$	
∇_b	$m^a abla_b \ell_a$	$\frac{1}{2}(n^a \nabla_b \ell_a - \bar{m}^a \nabla_b m_a)$	$-\bar{m}^a abla_b n_a$	
D	κ	ϵ	π	(20)
Δ	au	γ	ν	(20)
δ	σ	β	μ	
δ	ρ	α	λ	

These are known as the NP spin coefficients.

As $\nabla_{BB'}$ is torsion free, we can also write down the commutators for the derivations.

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Using the spinor dyad (o^A , ι^A) we can also write down the NP **curvature scalars**:

$$\begin{split} \Phi_{00} &= \Phi_{ABA'B'} o^A o^B \bar{o}^{A'} \bar{o}^{B'}, \ \Phi_{11} &= \Phi_{ABA'B'} o^{A} \iota^B \bar{o}^{A'} \bar{\iota}^{B'}, \ \Phi_{22} &= \Phi_{ABA'B'} \iota^A \iota^B \bar{\iota}^{A'} \bar{\iota}^{B'}, \\ \Phi_{01} &= \Phi_{ABA'B'} o^A o^B \bar{o}^{A'} \bar{\iota}^{B'}, \ \Phi_{10} &= \Phi_{ABA'B'} o^{A} \iota^B \bar{o}^{A'} \bar{o}^{B'}, \\ \Phi_{02} &= \Phi_{ABA'B'} o^A o^B \bar{\iota}^{A'} \bar{\iota}^{B'}, \ \Phi_{20} &= \Phi_{ABA'B'} \iota^A \iota^B \bar{o}^{A'} \bar{o}^{B'}, \\ \Phi_{12} &= \Phi_{ABA'B'} o^A \iota^B \bar{\iota}^{A'} \bar{\iota}^{B'}, \ \Phi_{21} &= \Phi_{ABA'B'} \iota^A \iota^B \bar{o}^{A'} \bar{\iota}^{B'}. \end{split}$$

$$\begin{split} \Psi_0 &= \Psi_{ABCD} o^A o^B o^C o^D, \ \Psi_1 &= \Psi_{ABCD} o^A o^B o^C \iota^D, \\ \Psi_2 &= \Psi_{ABCD} o^A o^B \iota^C \iota^D, \ \Psi_3 &= \Psi_{ABCD} o^A \iota^B \iota^C \iota^D, \\ \Psi_4 &= \Psi_{ABCD} \iota^A \iota^B \iota^C \iota^D. \end{split}$$

We could write down the Ricci equations, $R_{abcd} = 2e_{ia}\nabla_{[c}\nabla_{d]}e_{b}^{i}$, and Bianchi identities, $R_{ab[cd;e]} = 0$ in terms of these quantities.

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As an example, we will consider the vacuum type N spacetimes [Collins, 1991], so that

$$\Lambda=0, \ \Phi_{ABA'B'}=0 \ \text{and} \ \Psi_0=\Psi_1=\Psi_2=\Psi_3=0$$

according to the Petrov classification.

This is done using a rotation to fix the principal spinor $\alpha^A = o^A$.

We can also employ a Lorentz transformations to set $\Psi_4 = 1$.

The Bianchi identities, Rab[cd;e] are then

$$\begin{aligned}
\kappa &= 0, \\
\sigma &= 0, \\
4\epsilon &= \rho, \\
4\beta &= \tau
\end{aligned}$$
(21)

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NP "field" equations

The Ricci equations, $R_{abcd} = 2e_{ia} \nabla_{[c} \nabla_{d]} e^{i}_{b}$, are

$$D\rho = \frac{5}{4}\rho^2 + \frac{1}{4}\rho\bar{\rho}$$
 (2.4*a*)

$$D\tau = \frac{5}{4}\rho\tau + \bar{\pi}\rho - \frac{1}{4}\bar{\rho}\tau \tag{2.4b}$$

$$D\alpha - \frac{1}{4}\bar{\delta\rho} = \frac{1}{2}\rho\alpha + \frac{1}{4}\bar{\rho}\alpha - \frac{1}{16}\bar{\tau}\rho + \frac{5}{4}\rho\pi$$
(2.4c)

$$D\gamma - \frac{1}{4}\Delta\rho = \frac{5}{4}\tau\pi - \frac{1}{2}\gamma\rho + \tau\alpha + \alpha\bar{\pi} + \frac{1}{4}\tau\bar{\tau} - \frac{1}{4}\bar{\gamma}\rho - \frac{1}{4}\gamma\bar{\rho}$$
(2.4d)

$$D\lambda - \bar{\delta}\pi = \frac{1}{4}\rho\lambda + \frac{1}{4}\bar{\rho}\lambda + \pi^2 + \alpha\pi - \frac{1}{4}\bar{\tau}\pi$$
(2.4e)

$$D\mu - \delta\pi = \frac{3}{4}\bar{\rho}\mu + \pi\bar{\pi} - \frac{1}{4}\rho\mu - \pi\bar{\alpha} + \frac{1}{4}\pi\tau$$
(2.4f)

$$D\nu - \Delta\pi = \pi\mu + \bar{\tau}\mu + \bar{\pi}\lambda + \tau\lambda + \gamma\pi - \bar{\gamma}\pi - \frac{3}{4}\rho\nu - \frac{1}{4}\bar{\rho}\nu \qquad (2.4g)$$

$$\Delta\lambda - \bar{\delta}\nu = -\mu\lambda - \bar{\mu}\lambda - 3\gamma\lambda + \bar{\gamma}\lambda + 3\alpha\nu + \pi\nu - \frac{3}{4}\bar{\tau}\nu - \Psi_4 \qquad (2.4h)$$

$$\delta\rho = \frac{5}{4}\tau\rho + \bar{\alpha}\rho - \bar{\rho}\tau \tag{2.4i}$$

$$\delta\alpha - \frac{1}{4}\bar{\delta\tau} = \frac{5}{4}\mu\rho + \alpha\bar{\alpha} + \frac{1}{16}\tau\bar{\tau} - \frac{1}{2}\alpha\tau + \gamma\rho - \gamma\bar{\rho} - \frac{1}{4}\rho\bar{\mu}$$
(2.4*j*)

$$\delta\lambda - \bar{\delta}\mu = \rho\nu - \bar{\rho}\nu + \mu\pi - \bar{\mu}\pi + \mu\alpha + \frac{1}{4}\mu\bar{\tau} + \lambda\bar{\alpha} - \frac{3}{4}\lambda\tau \qquad (2.4k)$$

$$\delta\nu - \Delta\mu = \mu^2 + \lambda\bar{\lambda} + \gamma\mu + \bar{\gamma}\mu - \bar{\nu}\pi + \frac{1}{4}\tau\nu - \bar{\alpha}\nu$$
(2.41)

$$\delta\gamma - \frac{1}{4}\Delta\tau = \frac{1}{2}\tau\gamma - \bar{\alpha}\gamma + \frac{5}{4}\mu\tau - \frac{1}{4}\rho\bar{\nu} + \frac{1}{4}\tau\bar{\gamma} + \alpha\bar{\lambda}$$
(2.4*m*)

$$\delta\tau = \lambda\rho + \frac{3}{4}\tau^2 - \tau\tilde{\alpha} \tag{2.4n}$$

$$\Delta \rho - \delta \tau = -\rho \bar{\mu} - \frac{3}{4} \bar{\tau} \tau - \alpha \tau + \gamma \rho + \bar{\gamma} \rho \tag{2.40}$$

$$\Delta \alpha - \bar{\delta} \gamma = \frac{5}{4} \rho \nu - \frac{5}{4} \tau \lambda + \bar{\gamma} \bar{\alpha} - \bar{\mu} \bar{\alpha} - \frac{3}{4} \tau \gamma.$$
(2.4*p*)

Figure: Taken from [Collins, 1991]

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Type N subclasses

pp-wave metrics

$$\rho = 0, \ \tau = 0.$$

• Rotating plane-fronted wave metrics (Kundt waves)

$$\rho = \mathbf{0}, \ \tau \neq \mathbf{0}.$$

Robinson-Trautman metrics

$$ho
eq 0, Im(
ho) = 0.$$

The twisting case

$$\rho \neq 0, Im(\rho) \neq 0.$$

So far, only the Hauser metric is the sole example of vacuum type N spacetimes with twist.

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The Cartan-Karlhede Algorithm

Denote the set of components $\{R_{abcd}, R_{abcd;e_1}, \dots, e_q\}$ as R^q .

The algorithm is then:

- Let *q* = 0.
- Compute R^q.
- Fix the frame as much as possible using Lorentz frame transformations.
- **9** Find the invariance group H^q of the frame which leaves R^q invariant.
- Solution Find the number of functionally independent components t^q amongst the set R^q .
- If $t^q \neq t^{q-1}$ or $dim(H^q) \neq dim(H^{q-1})$ then set q = q + 1 and go to step 2. Otherwise, the algorithm stops and set q = p + 1.

The set $\{H^r, t^r, R^r\}, r = 1, ..., p + 1$ classifies the solution, locally.

Definition

The set R^{ρ} relative to the frame basis determined by the Cartan-Karlhede algorithm are called *Cartan invariants*.

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First order derivatives

$$(D\Psi)_{\hat{\mu}E'} = \Psi_{ABCD;EE'}\epsilon_{I}^{A}\epsilon_{J}^{B}\epsilon_{K}^{C}\epsilon_{L}^{D}\epsilon_{M}^{E}\epsilon_{M'}^{E'}$$

$$= (\Psi_{ABCD}\epsilon_{I}^{A}\epsilon_{J}^{B}\epsilon_{K}^{C}\epsilon_{L}^{D})_{:EE'}\epsilon_{M}^{E}\epsilon_{M'}^{E'} - (\epsilon_{I}^{A}\epsilon_{J}^{B}\epsilon_{K}^{C}\epsilon_{L}^{D})_{EE'}\epsilon_{M}^{E}\epsilon_{M'}^{E'}\Psi_{ABCD},$$
(22)

where, $\hat{\mu}$ counts the appearance of ι . There are 3 cases:

$$\begin{aligned} \hat{\mu} &= 5 : (D\Psi)_{\hat{\mu}E'} = (\Psi_4)_{;1E'} - 4\Gamma_{111E'}\Psi_3 + 4\Gamma_{101E'}\Psi_4, \\ \hat{\mu} &= 4 : (D\Psi)_{\hat{\mu}E'} = (\Psi_4)_{;0E'} - 4\Gamma_{110E'}\Psi_3 + 4\Gamma_{100E'}\Psi_4, \\ \hat{\mu} &< 4 : (D\Psi)_{\hat{\mu}E'} = (\Psi_{\hat{\mu}})_{;0E'} - \hat{\mu}\Gamma_{1110E'}\Psi_{\hat{\mu}-1} + \hat{\mu}\Gamma_{100E'}\Psi_{\hat{\mu}} - (2\hat{\mu} - 4)\Gamma_{100E'}\Psi_{\hat{\mu}} \\ &+ (4 - \hat{\mu})\Gamma_{000E'}\Psi_{\hat{\mu}+1}. \end{aligned}$$
(23)

In the vacuum type N spacetimes we find:

$$\begin{array}{l} (D\Psi)_{40'} = \rho, \\ (D\Psi)_{50'} = 4\alpha, \\ (D\Psi)_{41'} = \tau, \\ (D\Psi)_{51'} = 4\gamma. \end{array}$$

$$(24)$$

Second derivatives

$$(D^{2}\Psi)_{\hat{\mu}E';FF'} = \Psi_{ABCD;EE';FF'}[\epsilon_{I}^{A}\epsilon_{J}^{B}\epsilon_{K}^{C}\epsilon_{L}^{D}\epsilon_{M}^{E}]\epsilon_{M'}^{E'}\epsilon_{N}^{F}\epsilon_{N'}^{F'},$$
(25)

or with the Leibnitz rule ...

$$(D^{2}\Psi)_{\hat{\mu}E';FF'} = (\Psi_{ABCD;EE'}\epsilon_{l}^{A}\epsilon_{J}^{B}\epsilon_{K}^{C}\epsilon_{L}^{D}\epsilon_{M}^{E}]\epsilon_{M'}^{E'})_{;FF'}\epsilon_{N}^{F}\epsilon_{N'}^{F'} - (\epsilon_{l}^{A}\epsilon_{J}^{B}\epsilon_{K}^{C}\epsilon_{L}^{D}\epsilon_{M}^{E}]\epsilon_{M'}^{E'})_{;FF'}\epsilon_{N}^{F}\epsilon_{N'}^{F'}\Psi_{ABCD;EE'}.$$
(26)

With some work, this can be written as

$$(D^{2}\Psi)_{\hat{\mu}E';FF'} = [(D\Psi)_{\hat{\mu}E'}]_{;FF'} - \hat{\mu}\Gamma_{11FF'}(D\Psi)_{(\hat{\mu}-1)E'} + (2\hat{\mu}-5)\Gamma_{10FF'}(D\Psi)_{\hat{\mu}E'} + (5-\hat{\mu})\Gamma_{00FF'}(D\Psi)_{(\hat{\mu}+1)E'} - \bar{\Gamma}_{E'1'F'F}(D\Psi)_{\hat{\mu}0'} + \bar{\Gamma}_{E'0'F'F}(D\Psi)_{\hat{\mu}1'}.$$

$$(27)$$

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Vacuum type N spacetimes

$$\begin{split} &(D^{2}\Psi)_{30';10'}=2\rho^{2},\\ &(D^{2}\Psi)_{30';11'}=2\rho\tau,\\ &(D^{2}\Psi)_{31';10'}=2\rho\tau,\\ &(D^{2}\Psi)_{31';11'}=2\tau^{2},\\ &(D^{2}\Psi)_{40';00'}=D\rho+\frac{3}{4}\rho^{2}-\frac{1}{4}|\rho|^{2},\\ &(D^{2}\Psi)_{40';10'}=\bar{\delta}\rho+7\alpha\rho-\frac{1}{4}\bar{\tau}\rho,\\ &(D^{2}\Psi)_{40';01'}=\delta\rho+\frac{3}{4}\tau\rho-\bar{\alpha}\rho+\tau\bar{\rho},\\ &(D^{2}\Psi)_{40';01'}=\delta\rho+\frac{3}{4}\rho\tau-\bar{\alpha}\rho+\tau\bar{\rho}+|\tau|^{2},\\ &(D^{2}\Psi)_{41';00'}=D\tau+\frac{3}{4}\rho\tau-\bar{\pi}\rho+\frac{1}{4}\bar{\rho}\tau,\\ &(D^{2}\Psi)_{41';10'}=\bar{\delta}\tau+3\alpha\tau+4\gamma\rho-\bar{\mu}\rho+\frac{1}{4}|\tau|^{2}, \end{split}$$

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Vacuum type N spacetimes

$$\begin{split} (D^{2}\Psi)_{41';01'} &= \delta\tau + \frac{3}{4}\tau^{2} - \bar{\lambda}\rho + \bar{\alpha}\tau, \\ (D^{2}\Psi)_{41';11'} &= \Delta\tau + 7\gamma\tau - \bar{\nu}\rho + \bar{\gamma}\tau, \\ (D^{2}\Psi)_{50';00'} &= 4D\alpha - 5\pi\rho + 5\alpha\rho - \bar{\rho}\alpha, \\ (D^{2}\Psi)_{50';10'} &= 4\bar{\delta}\alpha - 5\lambda\rho + 20\alpha^{2} - \bar{\tau}\alpha, \\ (D^{2}\Psi)_{50';01'} &= 4\delta\alpha - 5\mu\rho + 5\tau\alpha - 4|\alpha|^{2} + 4\gamma\bar{\rho}, \\ (D^{2}\Psi)_{50';11'} &= 4\Delta\alpha - 5\nu\rho + 20\gamma\alpha - 4\bar{\gamma}\alpha + 4\gamma\bar{\tau}, \\ (D^{2}\Psi)_{51';10'} &= 4\bar{D}\gamma - 5\pi\tau + 5\rho\gamma - 4\bar{\pi}\alpha + \bar{\rho}\gamma, \\ (D^{2}\Psi)_{51';10'} &= 4\bar{\delta}\gamma - 5\lambda\tau + 20\alpha\gamma - 4\bar{\mu}\alpha + \bar{\tau}\gamma, \\ (D^{2}\Psi)_{51';01'} &= 4\delta\gamma - 5\mu\tau + 5\gamma\tau - 4\bar{\lambda}\alpha + 4\gamma\bar{\alpha}, \\ (D^{2}\Psi)_{51';11'} &= 4\Delta\gamma - 5\nu\tau + 20\gamma^{2} - 4\bar{\nu}\alpha + 4|\gamma|^{2}. \end{split}$$

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Linear Isotropy

We see that four spin-coefficients appear at first order:

$$\rho, \alpha, \tau, \text{ and } \gamma,$$
(28)

along with their derivatives at higher orders.

At zeroth order, we can transform the spin frame and leave the Type N condition unchanged:

$$o' = o, \iota' = \iota + bo \tag{29}$$

Under this transformation, the "first order" spin-coefficients above transform as

$$\rho' = \rho,$$

$$\alpha' = \alpha + \frac{5}{4}\bar{b}\rho,$$

$$\tau' = \tau + b\rho,$$

$$\gamma' = \gamma + b\alpha + \frac{5}{4}\bar{b}\tau + \frac{5}{4}|b|^{2}\rho.$$
(30)

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Summary of Collins' analysis

	1	lla	IIb	Illa	IIIb
Invariant	ho eq 0	ho = 0	ho = 0	ho = 0	ho = 0
characterization		au= 0	au= 0	au eq 0	au eq 0
		$\alpha \neq 0$	$\alpha = 0$	$ \alpha \neq \frac{5}{4} \tau $	$ \alpha = \frac{5}{4} \tau $
Canonical form:					
Zeroth order	$\Psi_i = \delta^4_i$	$\Psi_i = \delta^4_i$	$\Psi_i = \delta_i^4$	$\Psi_i = \delta^4_i$	$\Psi_i = \delta_i^4$
First order	$ au = 0^{T}$	$\gamma = 0$		$\gamma = 0$	$Re(\gamma)$ or $Im(\dot{\gamma}) = 0$
Second order					$\textit{Re}(\Delta au) = 0$
Upper bound	5	4	2	5 4	ø ø 3

- In case III, Collins (1991) provided an upper-bound of 5 and 6 for a and b respectively.
- Ramos and Vickers (1996) using the GHP formalism gave an upper-bound of 5 for III [Ramos and Vickers, 1996]
- DDM. Milson and Coley (2013) lowered the upper-bounds and provided examples, showing they were sharp [McNutt et al., 2013].

Motivation Boosts! Alignment classification in 4D

The Cartan-Karlhede Algorithm

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The algorithm is then:

- Let *q* = 0.
- Compute R^q.
- **③** Fix the frame as much as possible using Lorentz frame transformations.
- **9** Find the invariance group H^q of the frame which leaves R^q invariant.
- Solution Find the number of functionally independent components t^q amongst the set R^q .
- If $t^q \neq t^{q-1}$ or $dim(H^q) \neq dim(H^{q-1})$ then set q = q + 1 and go to step 2. Otherwise, the algorithm stops and set q = p + 1.

The set $\{H^r, t^r, R^r\}, r = 1, ..., p + 1$ classifies the solution, locally.

Definition

The set R^{ρ} relative to the frame basis determined by the Cartan-Karlhede algorithm are called *Cartan invariants*.

Motivation Boosts! Alignment classification in 4D

4D: Higher rank spinors/tensors

We can treat the Weyl tensor, C_{abcd} and the Ricci tensor, R_{ab} , as operators on some vector space and fin canonical forms of the operators.

For example, the self dual Weyl tensor

$$C_{abcd}^{*} = C_{abcd} + i \frac{1}{2} C_{ab}^{ef} \epsilon_{efcd}$$
(31)

can be seen as an operator acting on the 6-dimensional space of self dual bivectors, $X^*_{ab} = -i\frac{1}{2}\epsilon_{abcd}X^{*cd}$:

$$C_{ab}^{* \ cd} X_{cd}^{*} = Y_{ab}^{*}$$
 (32)

Can we treat $C^*_{abcd;e}$ or $R_{ab;e}$ as operators on some vector space? In general, no.

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Recall the Weyl spinor

$$\Psi = \Psi_{IJKL} \epsilon^{I}{}_{A} \epsilon^{J}{}_{B} \epsilon^{K}{}_{C} \epsilon^{L}{}_{D}$$
(33)

We can count the number of principal spinors, o^A and relate these to principal null directions of the self-dual tensor

$$C^*_{abcd} = 2\Psi_{ABCD}\epsilon_{A'B'}\epsilon_{C'D'} \tag{34}$$

To count the number of appearance of o^a in each term, we can consider a boost:

$$o' = ao, \ \iota' = a^{-1}\iota, \leftrightarrow \ell' = a^{2}\ell, \ n' = a^{-2}n$$
 (35)

In this representation, we find that

$$\Psi_0' = a^4 \Psi_0, \ \Psi_1' = a^2 \Psi_1, \ \Psi_2' = \Psi_2, \ \Psi_3' = a^{-2} \Psi_3, \ \Psi_4' = a^{-4} \Psi_4.$$
 (36)

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More generally, consider a boost for an arbitrary tensor [Milson et al., 2005],

$$T'_{a_1 a_2 \dots a_n} = \lambda^{b_{a_1 a_2 \dots a_n}} T_{a_1 a_2 \dots a_n},$$
(37)

The quantity,

$$b_{a_1a_2...a_n} = \sum_{i=1}^n (\delta_{a_i0} - \delta_{a_i1})$$

is called the *boost weight* (b.w) of the frame component $T_{a_1a_2...a_p}$.

We can write the tensor T in the following decomposition:

$$\mathbf{T} = \sum_{b} (\mathbf{T})_{b}.$$
 (38)

 $(\mathbf{T})_b$ denotes the projection onto the subspace of components of boost weight b.

Alignment classification

For any T we can pick an NP frame and decompose into b.w.:

$$\mathbf{T} = \sum_{b} (\mathbf{T})_{b}. \tag{39}$$

Boost order, $\mathcal{B}_{T}(\ell)$, is the maximum b.w. of a tensor, T, for a null direction ℓ .

For a given null direction ℓ , $\mathcal{B}_T(\ell)$ is invariant under boosts, spatial rotations and null rotations about ℓ .

 $\mathcal{B}_{T}(\ell)$ is only dependent on the choice of ℓ .

Defining

$$B_{\mathbf{T}} = \max_{\ell} \mathcal{B}_{\mathbf{T}}(\ell)) \tag{40}$$

the existence of a ℓ with $\mathcal{B}_{T}(\ell) < B_{T}$ is an invariant property of the tensor **T**.

We will say ℓ is **T**-aligned if $\mathcal{B}_{T}(\ell) < B_{T}$.

More Spinors	
An example in 4D	
The alignment classification	Alignment classification in 4D

To determine the canonical form of R_{abcd} , consider the effect of a boost on its irreducible parts:

Alignment types of the Weyl tensor, Cabcd, and Ricci tensor, Rab, are

Туре	G	1	Ш	111	Ν	(42)
$\mathcal{B}_{T}(\ell)$	2	1	0	-1	-2.	(42)

If C_{abcd} or R_{ab} vanishes, then it belongs to alignment type **O**.

Alignment type is not enough to reproduce Segre type for R_{ab} , instead we must also examine the algebro-geometric properties of

$$R'_{00} = R_{00} + 2R_{0i}c^{i} + R_{ij}c^{i}c^{j} - R_{01}|c|^{2} - R_{1i}c^{j}|c|^{2} + R_{11}|c|^{4} = 0.$$
(43)

More Spinors	
An example in 4D	
he alignment classification	Alignment classification in 4D

For $R_{abcd,e_1...e_p}$, $|\mathcal{B}_{\mathbf{T}}(\ell)|$ may be greater than two but the alignment types are still applicable.

For example, here are the b.w. of the first covariant derivative:

$$b = -3 : C^*_{1212;1} = 8\alpha,$$

$$b = -2 : C^*_{0112;1} = C^*_{1201;1} = C^*_{1212;3} = C^*_{1223;2} = C^*_{2312;1} = -2\rho,$$

$$b = -2 : C^*_{1212;2} = 8\gamma,$$

$$b = -1 : C^*_{0112;2} = C^*_{1201;2} = C^*_{1212;0} = C^*_{1223;2} = C^*_{2312;2} = -2\tau.$$
(44)

We can consider the transformation rules from before

$$\rho' = \rho,$$

$$\alpha' = \alpha + \frac{5}{4}\bar{b}\rho,$$

$$\tau' = \tau + b\rho,$$

$$\gamma' = \gamma + b\alpha + \frac{5}{4}\bar{b}\tau + \frac{5}{4}|a|^{2}\rho.$$
(45)

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More Spinors	Motivation
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Conclusions

Invariant characterization	ho eq 0	$ \begin{aligned} & \textit{Ila} \\ & \rho = 0 \\ & \tau = 0 \\ & \alpha \neq 0 \end{aligned} $	$ \begin{matrix} \textit{Ilb} \\ \rho = 0 \\ \tau = 0 \\ \alpha = 0 \end{matrix} $	$ \begin{aligned} & \text{IIIa} \\ & \rho = 0 \\ & \tau \neq 0 \\ & \alpha \neq \frac{5}{4} \tau \end{aligned} $	$ \begin{aligned} & \textit{IIIb} \\ & \rho = 0 \\ & \tau \neq 0 \\ & \alpha = \frac{5}{4} \tau \end{aligned} $
Canonical form: Zeroth order First order Second order	$\begin{aligned} \Psi_i &= \delta^4_{\ i} \\ \tau &= 0 \end{aligned}$	$ \begin{aligned} \Psi_i &= \delta_i^4 \\ \gamma &= 0 \end{aligned} $	$\Psi_i = \delta^4_{\ i}$	$ \begin{aligned} \Psi_i &= \delta_i^4 \\ \gamma &= 0 \end{aligned} $	$\Psi_{i} = \delta_{i}^{4}$ $Re(\gamma) \text{ or } Im(\gamma) = 0$ $Re(\Delta \tau) = 0$
Upper bound	5	4	2	4	3

At first order $|\mathcal{B}_{T}(\ell)|$ is not enough to distinguish some cases

Subclass	1	lla	IIb	Illa	IIIb	(46)
$ \mathcal{B}_{T}(\ell) $	-2	-3	-2	-1	-1	(40)

Coarse canonical forms that can be refined by adding additional geometric conditions.

This is still an open question on how.

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Motivation Boosts! Alignment classification in 4D

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More Spinors	
An example in 4D	
The alignment classification	Alignment classification in 4D

Thank you for your attention!

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